MANUFACTURING & TESTING OF COMPOSITE HYBRID LEAF SPRIGN FOR AUTOMOTIVE APPLICATIONS

by

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Dedicated to my parents Rajesh and Ruchi Agrawal

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ABSTRACT

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Leaf springs are a part of the suspension system attached between the axle and the chassis of the vehicle to support weight and provide shock absorbing capacity of the vehicle. For more than half a century the leaf springs are being made of steel which increases the weight of the vehicle and is prone to rusting and failure. The current study explores the feasibility of composite leaf spring to reduce weight by designing, manufacturing and testing the leaf spring for the required load cases. An off the shelf leaf spring of Ford F-150 is chosen for making of composite hybrid spring prototype. The composite hybrid prototype was made by replacing all the leaves with glass fiber unidirectional laminate except the first leaf. Fatigue tests are then done on steel and composite hybrid leaf spring to observe the failure locations and mechanism if any. High frequency fatigue tests were then done on composite beams with varying aspect ratio in a displacement-controlled mode to observe fatigue location and mechanism of just glass fiber composite laminate. It was observed that specimens with low aspect ratio failed from crack propagation initiated from stress concentrations at the loading tip in 3-point cyclic flexure test and shear forces played a dominant role in propagation of crack. Specimens with high aspect ratio under the same loading did not fail in cyclic loading and preserved the same stiffness as before the cyclic loading. The preliminary fatigue results for high aspect ratio composite beams predict a promising future for multi-leaf composite springs.

1. INTRODUCTION

1.1 Overview of composites

The increase in regulations against pollution and the race to achieve higher efficiency has forced the industries to focus on alternate materials which are lighter and can be easily processed. Composites fit in the solution to the problem. Composites are a combination of two or more different materials whose combination produce completely different properties compared to individual material properties[1]. The materials in composites can be distinguished using appropriate methods as they do not blend into each other. Composites occur naturally and are also made in the industries. Examples of naturally occurring composites include wood which is a combination of long cellulose fibers and lignin which is a weaker substance and holds the fibers together. Cotton also contains cellulose but lacks lignin and hence there is nothing to bind the fibers which makes it much weaker to wood for structural applications. Another example of composite is the bone in human body which is made of hydroxyapatite and collagen which is a soft and flexible material and binds hydroxyapatite together. All these examples have one thing in common which is that there is a binder, also called matrix, which binds the fibers or fragments of other material which is also called the reinforcement. Different types of fibers are available in the market and the most commonly used fibers are glass and carbon. There are different polymers available for binding the fibers and the polymers are broadly categorized into two categories which are thermosets and thermoplastics. The main difference between thermosets and thermoplastics is that thermoplastics can be melted back to conform to the original shape whereas thermosets once formed cannot be conformed back into original shape by applying temperature[2]. Thermoplastic polymers flow with the increase of temperature and solidify when cooled. The polymer chains flow to restructure themselves but no chemical reaction takes place between the strands of the chain whereas with the thermoset polymers there is chemical reaction which takes place between different chains which cannot be reserved and hence the chains are entangled and cannot retain their original shape with the increase in temperature.



Figure 1.1 - Molecular structure for thermoplastic and thermoset resins [3]

Figure 1.1 shows the formation of permanent bonds in thermoset polymers which avoid conforming to the original shape with the application of heat. There are various processes using which composite parts can be manufactured. The manufacturing process for composites generally require some form of mold which is required to give shape to the part during the curing process. Curing is the process by which the resin hardens to form a solid shape which cannot be conformed back into original shape in case of thermoset polymers. The most common way of manufacturing composite parts is using hand layup. The process consists of placing plies of dry fabrics or prepregs (pre-impregnated fibers with resin) to form a laminate stack. In case of dry fibers, the resin is coated on the fibers and in case of prepregs the resin is already impregnated with the fibers. The laminate stack is then compacted with the application of force using rollers or compaction press. The most common method of compacting the laminate stack is vacuum bagging the laminate stack. The vacuum pressure compacts the laminate stack and sucks out the air bubbles which might create voids in the curing process. This is achieved by sealing the tool edges with the plastic bag using high strength double sided tape. Vacuum ports are kept inside the plastic bag which is then used to remove air using air hoses and vacuum pump. The part is then cured in the autoclave which is temperature and pressure-controlled vessel according to the curing time cycles of the polymer [4]. The process is used when high quality parts are required like in the aviation industry. The process is done in a controlled environment to avoid the accumulation of dust particles which might create voids and hence possible failure locations.



Figure 1.2 - Process explaining making of laminates using prepregs



Figure 1.3 - Large size autoclave

Autoclave manufacturing is a time consuming and costly process and is not scalable to automotive industry standards. Compression molding is a high-volume process that employs expensive metal dies in the shape of the part and the charge is pressed into the shape of the mold by the application of force with the heated dies accelerating the curing process. Generally snap cure resin is used in such processes as the cure time of such resin systems is low. The charge can be made of sheet molding compound or chopped thermoplastic platelets or prepregs cut into required shape. For the easy flow of the fibers while using prepregs small slits are made in the prepregs such that the length

of the fibers reduces or the long fibers will not flow in small dimensions of the tool. The typical process for SMC's includes cutting them in required shape to form the charge and the charge is heated with the mold to the point where the viscosity of the charge is minimum and the mold is then pressed at the required temperature. The feasibility of compression molding is being explored on a vast scale in aviation as well as automotive industry. Automakers are studying the feasibility to make exterior car body panels using carbon fiber SMC's to take advantage of the high stiffness to weight ratio of composites. New snap cure resins are being developed to prevent micro-cracking, UV, impact and moisture resistance with required surface quality demands.



Figure 1.4 - Process of making part using compression molding [5]

1.2 Overview of leaf spring

Leaf spring is an assembly of circular beams of different lengths clamped together to form a member which behaves as a spring for the suspension system in automobiles. The main purpose of a leaf spring is just like any other spring which is to absorb shocks by deformation in the elastic limit. Deformation beyond the elastic limit would lead to permanent strains and are avoided to avoid settling or premature failure. A typical leaf spring and its attachment in the vehicle is shown in the figure 1.5.



Figure 1.5 - Leaf spring assembly in automotive application [6]

The leaf spring can also be used as a structural member or attaching linkage unlike coil springs or torsion springs. This advantage is utilized while designing leaf spring to avoid extra linkage weights. The spring rate is defined as change in load per unit deflection and is different throughout the spring. The spring rate is also different in uninstalled and installed conditions due to clamping effects on the chassis which reduce the active length of the spring and thus increasing the clamped stiffness of the spring. One end of the spring is pinned with the chassis and at the other end shackle is attached to the vehicle. A shackle is a link with one end hinged to the chassis and the other to the leaf spring. Shackle eliminates the direct attachment of both the spring ends to the chassis which would lead to an indeterminate system.



Figure 1.6 - Shackle attachment at one end of the leaf spring [7]

The hinging of one end of the spring to the chassis and the other to the shackle allows the movement of leaf spring due to deflection from the load. The spring stiffness also varies as a function of shackle angle and hence the stiffness is variable when the leaf spring is attached in the automobile with the shackles. A big consideration while designing the suspension system is the ride comfort. A soft ride would require low stiffness of the suspension system and hence higher deflection of the spring. This can have a negative effect on many factors which are listed below:

- 1. A softer spring would lead to higher deflection and hence would be heavy due to increased length.
- 2. The softer spring would require larger ride clearance (distance between chassis and the spring) due to higher defection.
- The standing deflection of the vehicle due to its own weight would be much larger for a more flexible spring.

The standing deflection of the vehicle also affects braking, stability and cornering and hence due to space and design considerations it is not possible to make the suspension system as soft as possible. Ride clearance plays a major role in deciding the static deflection of the vehicle.

The two types of leaf spring fit in the automobiles are underslung and overslung leaf springs which are shown in figure 1.7.



Figure 1.7 - Overslung vs underslung leaf spring [8]

Figure 1.7 shows the difference between the overslung and the underslung springs. Overslung springs are supported at the top of the axle and the underslung are supported at the bottom of the axle using a U bolt. The low position of the spring in case of underslung spring lowers down the center of gravity of vehicle and helps in vertical stability but must be mounted low for stability from horizontal forces and this reduces the ground clearance of the vehicle. Another disadvantage of underslung leaf spring is that the clearance between the chassis and the axle is reduced which might lead to metal-metal contact between the chassis and the axle.

1.3 Previous work in composite leaf springs

The potential of saving upto 400 kg of weight from heavy commercial vehicle composite spring have been an interesting study topic for automotive industries. With the advancement of technology, composite springs are steadily finding its way for the suspension system for rail transportation. Composites being one-fifth the weight with almost same structural strength offer enhanced ride properties due to decreased unsprung weight and enhanced lateral stiffness. Extensive studies were done by the automobile industries in the late 1970s for checking the feasibility of composite leaf springs. The following studies done by various industries over a period of 10 years around 1970s is summarized below and details have been added to list out the gaps in the studies performed.

Bruce E. Kirkham et. al. [9] developed corvette liteflex composite spring. The target was to obtain half a million cycles without failure with less than 5% of the load drop which was successful. A random production composite spring even passed 10 million cycles to failure. Composite spring was also tested at low and high temperatures and after exposure to various chemicals like transmission oil, brake fluid, gasoline, water and many more. Stress relaxation with the number of cycles, noise isolation and vehicle handling were also studied. The spring was fit above the differential axle and near the exhaust and was subject to high temperatures from exhaust radiation as well as heating of differential. No problems occurred during the test which constituted of 800,000 durability kilometers and 4.5 million fleet test kilometers.

Kikuo Tanabe et. al. [10] from Nissan Motor Corporation performed tests on carbon/glass fiber reinforced leaf spring in the early 1980s. They made a composite leaf spring with combination of

glass and carbon fiber to increase spring stiffness. The figure 1.8 shows the schematic of the spring design.



Figure 1.8 - Mono leaf spring made using carbon and glass fiber with bolted end fasteners [10]

The spring was made with constant width but varying thickness along the length and steel eyes related to the composite beam using bolts. The beam was used with a combination of glass and carbon fiber with woven glass fiber and the ends and the center and unidirectional carbon fiber between the ends and the center to provide enhanced stiffness. The geometry of the mono leaf spring was made such that it is equally stiffer to the steel spring. It was found that the endurance of the composite spring was much higher than the steel spring and the static rate of the spring was equal to the steel spring but the decrease in lateral rate on lateral shake and ride handling was observed to be not significant. Both composite and steel spring had the same handling and lateral shake characteristics. The decrease in friction forces for composite leaf spring gives better ride handling on smooth roads. The composite leaf spring was also tested for stone chippings by testing the vehicle on rough road for 2000 kms. The damage observed was insignificant and had almost no effect on the endurance of the vehicle. The spring eyes were tested for longitudinal forces that exist in a running vehicle. The test setup used is shown in figure 1.9.



Figure 1.9 - Testing of spring bolted end fasteners for longitudinal forces [10]

The test vehicle considered had longitudinal forces for the spring around 10,000 N in the vehicle and the eye was loaded to 50,000 N without observing significant damage. The test was then stopped due to high observed factor of safety.

Terry N. Trebilcock and Joseph N. Epel [11] from The Budd Company designed, fabricated and field-tested leaf spring from fiberglass for a Ford van. Glass was chosen as the fiber and after several tests with different resin systems epoxy was chosen for the resin. Polyesters were not found suitable for fatigue and creep from lab tests. Vinyl esters were found suitable for fatigue or creep but were not suitable when tested for both fatigue and creep together. A constant cross section area design for the leaf spring with hyperbolic width profile was selected to be made using compression molding which is shown in figure 1.10.



Figure 1.10 - Constant area leaf with hyperbolic profile for compression molding [11]

The spring withstood 10⁶ cycles of vertical fatigue but failed in less than 50,000 cycles when braking torque was applied along with vertical deflection. The design was then modified to eliminate the stress concentrations caused by drilling holes and a full width end attachment was added to the leaf spring. The leaf spring was then again tested for endurance in braking and vertical deflection combined conditions. No failure was observed and test was suspended at 250,000 cycles which was above the criteria of 100,000 life cycles.

All the papers published in the 1970s by automobile companies mentioned above discuss the design of mono leaf composite springs and the characteristics of the test might be different for multi-leaf composite springs due to operational friction forces and the assembly stresses present in the leaf spring due for different curvatures of the leaf and was not studied. An attempt has been made in the thesis to study the effects of multi-leaf composite spring and how the aspect ratio would influence the fatigue properties of composite samples.

The mass production of composite leaf spring was delayed in the 1970s due to high cost of carbon and glass fibers and poor understanding of mass production methods for composites. In the current decade the low cost of glass fibers and advancement of manufacturing methods have led to commercialization of mono-leaf composite leaf spring and limited data is available in designing, manufacturing and testing of the commercially available products. The published literature available in the previous and current decade has been summarized below along with the shortcomings of the design.

Murathan Soner et. al. [12] compared the fatigue life of steel and composite mono leaf spring. The metal leaf spring weighed 26 kg and consisted of 2 leaves with rubber spacers between the leaves. Figure 1.11 shows the steel spring prototype tested for fatigue.



Figure 1.11 – Steel prototype spring [12]

The steel spring was tested for fatigue for a given load range for 200,000 cycles. 5 samples were tested and all passed the required cycle count. Carbon fiber and glass fiber reinforced epoxy leaf spring was then developed using Resin transfer molding having the same stiffness as the metal spring for testing in the fatigue jig. The image of the carbon fiber spring being tested is shown in the figure 1.12.



Figure 1.12 - Fatigue and stiffness testing jig for composite leaf spring [12]

Glass fiber spring was also made and tested for the same load parameters. The carbon fiber spring weighing 4.2 kg failed at 342,125 cycles which is much above the required limit. In conclusion they observed 80% weight reduction without any decrease in the number of cycles to failure.

S. Vijayarangan et. al. [13] designed a constant cross section with varying thickness and width mono leaf composite spring to minimize the weight of the mono leaf composite spring using Genetic Algorithm. The final composite design was 74.6% lighter than the original steel leaf spring and the final design is shown in figure 1.13.



Figure 1.13 - Optimization of cross sectional design using genetic algorithm [13]

Hemasunder Banka et. al. [14] fabricated a multi-leaf composite leaf spring and experimentally determined the stiffness and weight and compared it the leaf spring weight. The stiffness was found to be low by 18% and 57% weight reduction was observed for composite leaf spring. However, no fatigue tests were done to determine the number of fatigue cycles to failure.

H.A. Al-Qureshi [15] manufactured composite glass fiber spring using hand layup vacuum bagging method and cured at room temperature. The first design made had the steel end fasteners molded with the composite leaf and in the second design the fasteners were bolted with the composite spring. It was found that the spring with external bolted fasteners outperformed the initial design spring in fatigue endurance.

W.J. Yu [16] studied the double tapered glass fiber reinforced plastic composite spring and for static stiffness and fatigue endurance. The double tapered spring is shown in figure 1.14.



Figure 1.14 - Double tapered composite mono leaf spring [16]

Two prototypes were prepared with different glass fibers and were tested for 1 million fatigue cycles. One of them survived without any failure while the other had some observable damage on the tensile side of the spring but still retained the load carrying capacity of the vehicle. Also no hysteresis was observed with the max load in with fatigue cycles.

C. J. Morris [17] from Ford Motor Company manufactured composite leaf spring and conducted fatigue tests on proving grounds to validate the performance. The glass fiber spring acted as the transverse spring and was made using filament winded charge which was then compression molded. The figure 1.15 shows the manufacturing process for the spring.



Figure 1.15 - Process for making charge and compression molding of leaf spring [17]

The spring was tested in severe conditions at Dearbon proving grounds and no damage was observed to the composite spring but the end effectors to the spring used for the attachment to the chassis were damaged. They were then repaired and the test was continued and at the end no failure was observed to the composite spring.

In the current decade a new method for high rate manufacturing of composite leaf spring is being developed which involves the use of high-pressure resin transfer molding. Epoxy prepregs required the use of autoclave for high quality product part which is required in the aerospace industry but is time consuming and costly. New resin systems are formulated which are much lower in viscosity than traditional epoxy and require a fraction of curing time as compared to traditional epoxies. Loctile Max 2 resin developed by Henkel has a high modulus of 2800 MPa with a tensile strength of 80 MPa and high toughness which translates to fatigue resistance. Benteler-SGL and Henkel collaborated to use the newly developed resin Loctile Max 2 resin and reduced the curing time from 30 mins to a mere of 8 mins with urethane. The resin system was characterized to find the suitable injection temperature for viscosity as low as 30 mPas which leads to ultra-high injection speed of 100g to 300g to resin flow per second. Max 3 resin system was then launched by Henkel which also included a mold release agent with the formulation.

Snap cure resin systems are also being developed for medium to high volume production for composites. They provide fast cure but long enough injection window for impregnating the fibers. These chemicals are being developed by Momentive Specialty Chemicals based in Columbus, Ohio. At such high injection speed preform binder is very important to avoid the distortion of fibers with resin injection and negatively affect permeability of the preform. Low viscosity for flow and high impregnation time were essential for ensuring good quality of the part. EPIKOTE 05475 resin with EPIKURE 05443 curing agent developed by the company cures the part within 5 mins at 120°C. Combination of EPIKOTE 05475 resin, EPIKURE 05500 curing agent with Heloxy 112 internal mold release agent cures within 2 mins at 115°C [18].

Transverse leaf spring made of composite materials offer weight reduction as well as reduced number of elements. For transverse leaf spring conventional steel elements such as antiroll bar mounts and links, coil springs and two control arms are eliminated. The damping of composite structures leads to reduced transmission of vibration noise to adjacent structures.

Benteler-SGL and IFC composites in Germany are two of the few companies who have successfully commercialized the composite transverse leaf spring fitted in automobiles. Benteler-SGL uses HP-RTM for composite leaf spring production where as IFC uses compression molding of preforms for manufacturing leaf springs. Henkel's Loctile max 2 resin is used in high pressure RTM and with multiple cavities production rate as high as 500,000 parts per year can be achieved. The multicavity mold used for HP-RTM is shown in figure 1.16.



Figure 1.16 - Multicavity tool for resin transfer molding of leaf springs [19]

The leaf spring integrated with the chassis of the Volvo XC90 developed by Benteler-SGL is shown in figure 1.17.



Figure 1.17 - Transverse composite leaf spring for Volvo XC90 [20]

IFC composites also manufactures leaf spring but the process is different from Benteler-SGL. A unidirectional thick glass fiber prepreg is made in house by IFC composites and rolled to make a charge which is shown in figure 1.18.



Figure 1.18 - Use of rolled prepregs for leaf spring compression molding [21]

The charge is then compression molded using a press at 130 tons of force and the die temperatures are kept above 130°C for the resin to crosslink quickly. The final product is then post cured in the oven at elevated temperatures for complete curing of the part.



Figure 1.19 - Compression molding press [21]

The part is then fit in the automobiles as a transverse or longitudinal leaf spring with the help of metal fasteners as shown in figure 1.20.



Figure 1.20 - Attachment of leaf spring using metal fasteners [21]

All the research done in the field of composite leaf springs is done for mono-leaf composite spring being used as a transverse leaf spring or a longitudinal leaf spring for light commercial vehicles. Multi-leaf composite leaf spring as in the case of conventional steel leaf springs for heavy commercial vehicles is not studied in the literature. This work focusses on addressing issues in multi-leaf composite spring. An attempt has been made to manufacture and test composite hybrid leaf spring to understand how the stiffness changes with test cycles and failure mechanism. Another attempt has been made to study the effect of aspect ratio of composite samples on the cycles to failure and the corresponding mechanism.

2. THEORY BEHIND LEAF SPRING DESIGN

2.1 Design elements for leaf spring

2.1.1 Spring Eyes

The leaf spring assembly consists of the top leaf also called main leaf which contains the rounded ends also called eyes used for attaching the leaf spring with the automobile chassis and the individual supporting leafs are clamped together with the main leaf to provide the required stiffness. The eyes are made specific for certain purposes and the ends of the supporting leafs have different geometries to improve the load transfer between the supporting leafs and the main leaf. The spring ends used in the springs are shown in figure 2.1.



Figure 2.1 - Different ends (eyes) for the leaf spring assembly. Adapted from [22]

Upturned eye is the most commonly used eye for the leaf spring due to easy manufacturing.

Military wrapper design is widely used for military vehicles as the second leaf provides emergency support in case the main leaf eye breaks. The second leaf eye may also assist the main leaf eye in severe loads and rebounces where the two leafs come in contact and provide extra strength.

The plain end mounting type is used where the shackles cannot be fit due to space restrictions and the curved or flat end of the leaf spring is then supported against the curved of flat rubber pads for accommodating the change in length of the leaf spring due to deflection.

Downturned eye is used to provide a certain suspension motion to improve power steering or axle control and is not recommended if the support from the second leaf is required.

Berlin eye is used when horizontal forces are significant and the geometry avoids the eye to unwrap as compared to upturned eye. Berlin eye with military wrapper has the same function as military wrapper discussed above.

The welded eye is used where the horizontal forces are too high and might lead to unwrapping of the eye. The welding ensures that the eye is not unwrapped. The welding must be done before the heat treatment of the spring to avoid the formation of residual stresses.

Oval eye is used to reduce the magnitude of the horizontal forces in the suspension system and have rubber bushings with different rates in the vertical and the horizontal direction.

2.1.2 Leaf Ends

Leaf ends help in the transfer of load from one leaf to other and the design of leaf ends is essential in uniform stress distribution and obtaining the required stiffness. The figure 2.2 shows the different types of leaf ends that might exists in a leaf spring.



Figure 2.2 - Different types of leaf ends. Adapted from [22]

Square end – The edge of the leaf directly rubs on the leaf above thus creating stress concentrations due to the sharp edge and leads to increase in friction. It is a poor design for uniform strength spring and is heavier in weight than uniform stress spring.

End Tapered - The leafs are tapered using a roller and the tapering increases the contact area which leads to better load distribution and the taper can be controlled to give very close uniform stress distribution state for the leaf spring.

End trimmed with diamond point – The diamond point design is a better design than square end design and is a better approximation of the uniform stress state of the spring. The load transfer is slightly improved than the square end design for the leaf spring.

End squared and then trimmed – It is like the tapered end except to the fact that the end is later trimmed after the tapering operation and thus giving the maximum area of contact.

2.1.3 Center Bolt

Center Bolt – The center bolt is required to hold all leafs together and the head of the bolt is used for locating the position of installation on the axle. The head of the bolt should be below the

shortest leaf for overslung spring and above the main leaf for underslung spring. The torque applied to the bolt is high to cause deformations in the bolt so that the bolt does not loosen up due to vibrations. The portion of the leaf where center bolt is attached is not active while the leaf spring is in action due to fact that the area surrounding the center bolt is clamped and attached to the axle. The inactive length of the leaf spring depends upon the installation setup and generally vary between 8-15% of the leaf spring length. Since the region around the center bolt is clamped and inactive the stress concentrations occurring due to the hole geometry are not substantial to consider while designing. The diameter of the center bolt is recommended to be at least the thickness of the heaviest leaf to enable cold punching otherwise heating the area may be required to punch the hole of required size.

2.1.4 Center Clamp

Center Clamp – It is used to permanently tie the leaf spring with the seat surface on the axle of the vehicle using U bolts. The benefit of center clamp is that the spring remains in position and avoids the breaking of the center bolt due to horizontal forces. The width of the clamp reduces the active length of the spring and the ends are well rounded to avoid any sharp contact with the leaf spring. To effectively control the noise transmission rubber pads are used between the leaf spring and the clamp and the amount of softness is dictated by road holding, axle control and steering control.



Figure 2.3 - U bolt assembly used for clamping leaf spring to axle

2.1.5 Shackles

Shackle – Shackles are necessary links between the chassis and the leaf spring which allow the motion of one end of the leaf spring relative to the other with deflection of the spring. This avoids the problem of indeterminate system which would have been the case if both the ends of the leaf spring were hinged with the chassis. Shackles affect the rate of the spring with its angular position which lead to different ride characteristics from design. The figures 1.5 and 1.6 show the attachment of leaf spring in the vehicle.

2.1.6 Variable rate leaf spring

These types of leaf spring provide variable spring rate with the increase in load after a certain load. They are mainly used to vehicles in which the load variation is too high and ride comfort is required. Low stiffness for initial loads ensures better ride quality and the stiffness increases with the increase in load after a specific load limit. This ensures low stiffness at low loads and hence better ride quality and high stiffness at higher loads. The figure 2.4 shows the typical multistage spring resulting in variable stiffness of the spring.



Figure 2.4 - Side view of multistage variable rate leaf spring. Adapted from [22]

The first stage leaves are responsible for carrying the load until the second stage leaves comes in contact with the first stage leaves. With the second stage leaves coming in contact the stiffness of the leaf spring gradually increases and becomes constant with the complete contact of the second stage and the first stage leaves.

2.2 Design considerations and calculations for leaf spring

Beams in bending have a uniform cross section throughout the length and the variation in bending moment leads to non-uniform stress distribution across the length of the leaf spring. This leads to wastage of material as all section of material are not completely loaded to the max stress. The stress formula in a beam is given by equation 2.1.

$$\sigma = \frac{My}{I} \tag{2.1}$$

where M is the applied moment, y is the distance from the neutral axis and I is the moment of inertia. With the change in M, if the moment of inertia is also changed so that the stress remains at peak with a factor of safety then the resulting beam is called a beam with uniform strength. This leads to weight reduction and even distribution of stress along the leaf. Leaf springs are made using the consideration of uniform strength and hence the leaves are of different length. The figure 2.5 shows the description of the multi leaf spring.



Figure 2.5 - Different views for uniform strength beam. Adapted from [22]

Uniform section spring with the same load, length, thickness and stress produces two-third of the deflection and weighs twice as much as the uniform strength spring. Hence, the uniform strength spring is thrice as efficient as uniform section spring. By applying the Euler Bernoulli beam formulas, the stress and deflection can be found out using the load and the geometry of the beam.

The stress can be calculated from load as well as deflection and both formulas give an insight to the design of leaf spring. The stress from load formula is stated in the equation 2.2.

$$\sigma = \frac{My}{I} = \frac{6PLh}{bh^3} = \frac{6PL}{bh^2}$$
(2.2)

Where h is the leaf thickness, L the length of cantilever beam, b the width of the beam and P the applied load.

From formula 2.2 the stress is directly proportional to the length of the beam and inversely proportional to the square of the thickness of the beam. The stress from deflection formula states that the stress is directly proportional to the thickness of the beam and inversely proportional to the length square of the beam. The two formula seem paradoxical but in the stress from load formula the deflection is not considered and the stress from deflection formula can be obtained by substituting the load with stiffness times the deflection.

$$\sigma = \frac{My}{I} = \frac{6PL}{bh^2} = \frac{6K\delta L}{bh^2}$$
(2.3)

For a cantilever beam with load applied at one tip the deflection and load are related and given in equation 2.4.

$$\delta = \frac{PL^3}{3EI}, \qquad \qquad K = \frac{P}{\delta} = \frac{3EI}{L^3}$$
(2.4)

Substituting the value of k from equation 2.4 in equation 2.3 we get

$$\sigma = 6 * \frac{3EI}{L^3} * \frac{\delta L}{bh^2} = \frac{3}{2} * \frac{Eh\delta}{L^2}$$
(2.5)

The equation 2.5 directly relates the stress and displacement and states the stress is directly proportional to the leaf thickness and inversely proportional to the length square. The formula signifies that for given stress and deflection the thickness of the leaf is directly proportional to the square of the length. Since thin leafs cannot provide enough strength to the spring eyes the length of the spring should be increased to account for the increased thickness. Also, the windup stiffness varies as square of the length and hence it is desirable to have large length but the length is also constrained to the available space and the mounting points on the chassis.

Stiffening factor – The approximation of uniform strength for a leaf spring is not completely valid and the stresses need to be adjusted using a stiffening factor. The factors described below determine how closely the leaf spring matches the approximation for the uniform strength spring.

- Length of the leaves is not consistent with the uniform strength formula and this is specifically done for reduce the stress in the eye region. The length of the second leaf is sometimes made equal to the length of the main leaf to reduce the stress in the eye region.
- 2. Leaf ends of different geometries provide an approximation of uniform strength since they exceed the outline of the triangular beam.
- 3. Centre clamp reduces the active length of the spring and the procedure states testing of the leaf spring without the center clamp as the formulae are derived for the unclamped condition. The length in the formulae can be replaced by active length by subtracting the clamped length from the total length of the spring. The active length in the spring depends upon the clamping parts and the rubber pads used for support in the clamping of the leaf spring. In case of semi-elliptic cantilever beams the active length extends into the seat area and hence the active length is larger than the distance between the outside edge of the clamp and the point of application of load. In case of springs without liner material the active length is the distance from the load point to the inside edge of the clamp bolt.

The effect of the above-mentioned factors needs to be accounted for in the formulae with a stiffening factor which is denoted by SF. SF has an exact value of 1 when the leaves follow the length and thickness according to the ones derived from uniform strength formula. The farther the spring deviates from the uniform strength parameters the higher would be the stiffening factor. The value of SF ranges from 1 to 1.50 and the value 1 corresponds to uniform strength design
while the value of 1.5 corresponds to uniform cross section design. The table below summarizes the values of SF that should be used for different conditions for the preliminary design calculations.

S. No	Condition	SF
1	For passenger cars and light truck springs with tapered ends and more or less uniform stress design	1.1
2	For passenger cars and light truck springs with tapered ends and extended leaf lengths	1.15
3	For truck springs with untampered leaf ends with more or less uniform stress design	1.15
4	For truck springs with untampered leaf ends and two full length leaves	1.2
5	For truck springs with untampered leaf ends and three full length leaves	1.25
6	For the first stage of variable or progressive rate spring before contact with the second stage	1.40
7	For the second stage of variable or progressive rate spring when all leaves are operable, tapered leaf ends	1.10
8	For the second stage of variable or progressive rate spring when all leaves are operable, untapered leaf ends	1.15
9	For springs with all full-length leaves	1.50

Table 2.1 - Stiffening factor for different loading conditions

The table 2.1 shows all the formulae related with deflection and stress in leaf spring and are derived from Euler Bernoullli beam theory which considers the following facts.

- 1. The aspect ratio is large enough to ignore the shear stresses present in the beams.
- 2. Transverse cross section remains straight after bending and does not curve or warp.
- 3. The stress is then proportional to the bending moment multiplied by the leaf thickness divided by the moment of inertia.



Figure 2.6 - Original and deflected geometry of complete and half leaf spring. Adapted from [22]

S. No	Formula	Symmetrical Semi-Elliptic	Multi-leaf cantilever
		leaf spring	
1	Total moment of inertia -	$\sum L = L^3$	$\sum L L^3$
	mm^4	$\sum I = R * \frac{1}{32 * E * SF}$	$\sum I = R * \frac{1}{2 * E * SF}$
2	Maximum leaf thickness	$t = -\frac{8 * \Sigma I}{2} * \frac{S}{2}$	$t = \frac{2 * \sum I}{*} \frac{S}{S}$
	-mm	$c_{max} = \frac{1}{L} + \frac{1}{P}$	$c_{max} = \frac{1}{L} + \frac{1}{P}$
3	Stress with standard gage	S = L * t	S = L * t
	leaf – MPa	$S = \frac{1}{8 * \sum I} * P$	$3 - \frac{1}{2 \cdot \sum I} \cdot P$

Table 2.2 - Leaf thickness and stress formula for leaf spring calculations

The formulas in table 2.2 are valid for semi-elliptical leaf spring where the span of the spring on either side of the center bolt is equal. If the span is unequal and the span ratio is greater than a certain number then the formulas in table 2.2 cannot be used and different set of formulas should be used.

L- length of the semi-elliptic spring

1- length of cantilever spring

a – front length of the semi elliptic spring

b – rear length of the semi elliptic spring

P – load on spring

f – deflection on spring

k – load rate

 ΣI – total moment of inertia

 t_{max} – maximum leaf thickness

S – stress with selected gauge

SF – stiffening factor

The formulas discussed in table 2.2 are required for preliminary design calculations for spring. The first formula establishes the moment of inertia for the required rate and length. The 2nd formula tell the permissible leaf thickness at a corresponding load for a given max stress and the 3rd formula is used to calculate the maximum stress in the spring. For unsymmetrical springs with the length ratio of less than 1.3 the formulae corresponding to the symmetrical beams can be used but the results will not be completely accurate and within 3% of those obtained from complicated unsymmetrical beam formulae.

Leaf thickness obtained from the formulae signify the maximum leaf thickness that can be used but all leafs are not made with the same maximum gauge thickness. The main leaf is generally one gauge thicker than the shorter leafs and this is done to provide more strength to the eyes of the spring and more tolerance on quench radius on the shorter leaves. One other big reason for choosing leaves with different thicknesses is that the required moment of inertia is achieved more closely than using leaves with same gauge thickness. This helps in obtaining the load rate close to what is required in practice. Stepping – The length of different leaves in the spring determine the stress distribution along the length of the leaf. The shape and rate of the spring under load is determined by leaves length, thickness and leaf radii. The center of pressure is the point on the leaf where it contacts the upper leaf and the load transfer takes place and is different from the end of the leaf. In case of blunt ends the it may be 10 mm inside of the leaf end or in case of tapered leaf the distance may be as large as 50 mm inside the leaf. The distance between a point of contact and the adjacent point of contact is called the overhang. To determine the overhang of the shortest leaf the geometry of the clamp should be considered. All the overhangs summed together determine the active length of the spring. In case of beams shown in figure 2.7 where all the leaves are made of same thickness and radii, equal overhang or step would be given to resemble uniform strength spring as close as possible.



Figure 2.7 - Uniform overhang and thickness spring. Adapted from [22]

If the spring has different gauge thickness, then the step should be given proportional to t³. This would make the stresses uniform along the length of the leaf, but different leaves may be stresses differently which may not be beneficial for fatigue life endurance. Sometimes the second leaf is as the same length of the main leaf and this is done to reduce the stresses near the eye area and results in increase in stiffness of the spring. However, the stress at the edge of the clamps remain the same and if the load is increased then the stress would increase too no matter the length of other leaves. If springs with different curvatures are assembled together then assembly stresses are set up which are desirable for various other reasons. With the introduction of assembly stresses, it is impossible to have a uniform stress distribution across the length of the leaf for all loads. With suitable assembly stresses and leaf stepping the stresses can be made uniform along the length for a load. The spring when assembly with assembly stresses or assembled dead (same curvature for all leaf) have the same stiffness value for the same leaf radii, thickness and length.



The figure 2.8 shows the distribution of stresses with given loads with and without the assembly stresses.

Figure 2.8 - Stresses in leafs with and without assembly stresses. Adapted from [22]

With equal stepping of 250-250 the stresses are constant, and the design is most efficient with the lowest spring rate and deflects with uniform change in curvature. In the 400-100 stepping the spring behaves more likely uniform section spring. The introduction of 300 MPa assembly stresses the spring rate will be unaffected but the stress distribution and the deflection shape of the spring will change. Now 250-250 stepping is inefficient and the peak stress occurs at the tip of the second leaf. The stepping 325-175 gives a constant stress for a load of 100 N and the stress varies along the length for all other loads. The spring will have a circular shape under the load of 100 N. At other loads the shape will not be circular. For the 400-100 stepping the stress is uniform under a load of 50 N and the deformation would be circular for the load and for all other loads the shape would not be circular.



Figure 2.9 - Effect of assembly stresses on short and long leaves. Adapted from [22]

The figure 2.9 shows the effect of assembly stresses if the backing leaves are too short or too long. The spring is shown flat in the third case to bring out the changes to the in the desired shape if the backing leaves are too short or long. Practically the spring does not remain flat in service. In case of only moments applied to the spring the stresses would be constant throughout the spring and this condition can be fulfilled only if the load between the various leaves of the spring is equal to the load P at the end of the spring. The relation between uniform stress, thickness and overhang of the leaf is given in equation 2.5.

$$S_n = \frac{6*P*l_n}{w*t_n^2} \tag{2.5}$$

The subscript n refers to the nth leaf of the spring. Since the load and width of the spring is constant the overhangs l_n is proportional to $S_n t_n^2$.

$$l_n \propto S_n t_n^2 \tag{2.6}$$

Since the introduction to assembly stresses lead to uniform stress distribution only for a load it is important to decide what load should be selected for uniform stress distribution. For over the road vehicles experience has shown that if the stresses under the normal load are made uniform then best service is obtained.

The load transfer can take place between the leaves at a point or along the complete curvature. These two assumptions are called "point pressure" and "common curvature". For the point pressure method the leaves touch only at the ends and at the clamp center. This can be observed by the location of wear and tear after the spring has been in service. After calculating the tip load each individual spring can be considered as an individual beam for calculation. Generally, spacers are provided between the leaf at the center clamp to enable point contact and nylon pads are provided at the ends of the leafs to avoid metal to metal contact for friction and heat purposes. Common curvatures mean that all the length of the spring is in contact with the other leaf and the load transfer happens through the common curvature. This assumption leads to simpler calculations. In some cases the assumption of point pressure and common curvature leads to same results.

The analysis and design of a leaf spring can thus be considered as a combination of 4 stages:

- 1. Preliminary calculations for no of leaves, leaf thickness and stress.
- 2. Finding leaf length and radii of individual leaf and stress distribution at one load.
- 3. Finding stress at various points in the spring by common curvature or point pressure method.
- 4. Find the accuracy of the assumptions using a FEM model or strain gauges.

Strength of spring eyes – The eye of the spring will tend to open with the application of longitudinal forces due to braking or other shock forces. The formula for calculating the stress due to the horizontal forces is given in equation 2.7.

$$S = \frac{3F(D+t)}{t^2w} \tag{2.7}$$

The stress formula given in the equation applies to upturned, downturned and berlin eyes except in the case of berlin eyes that the stress is zero in case of compressive longitudinal forces which gives an added benefit to berlin eyes over the other two. In Hotchkiss drive suspension system a high factor of safety should be considered due to the presence of large horizontal braking and driving longitudinal forces. Hence, the maximum stress should not be allowed to increase than 350 MPa to ensure high safety factor.

Stresses due to press fitting of bushing in the eye can also be calculated from the formula 2.8.

$$S = \frac{4}{\pi} * \frac{\Delta Et}{(D+t)^2} \tag{2.8}$$

The stress due to press fit and longitudinal forces are additive in nature. Also, the axial force and torque obtained without slipping between the eye and the bushing will depend upon the finish, hardness and degree of lubrication of the engaging surfaces.

 Δ – Difference between OD of bushing and ID of eye

S-Stress

D - ID of the spring eye

- t Thickness of leaf at eye
- w Width of the leaf at eye
- E Modulus of elasticity (200 GPa)
- F Longitudinal forces

Installation effects – For the measurement of the spring stiffness the spring is deflected with load applied on the clamping area and rollers on the support for the spring to roll due to change in length of the spring. However, the spring stiffness varies when it is installed in the vehicles due to the installation of center clamps and shackles. By understanding the underlying mechanics of shackles and center clamp extensive installation testing can be avoided and the knowledge will be useful in obtaining the desired static or variable rates as required with the use of shackles.

With the installation of contact pads the active length of the spring decreases and effectively the rate of the spring would increase. In the attachment with the vehicle one eye is fixed and the other eye is shackled seen in figure 1.5 and 1.6.

With the load on the spring the length of the spring changes and the shackle would swing to accommodate the change in length of the spring. The shackle may lift or lower the eye during the process and the point of load application. This is called the first shackle effect. Also with the swing of the shackle it would be no longer perpendicular to the datum line of the spring and there would exists a horizontal or longitudinal force component either compressing or stretching the spring between the eyes. Stretching would increase the rate of the spring while compressing would decrease the rate of the spring. This is called the second shackle effect. Depending upon the location of hinging point of the shackle on the chassis the shackle can be termed as compression shackle or tension shackle. If the shackle hinging point is above the main leaf then the shackle in called the compression shackle.

The shackle effect depends upon the load on the spring rather than the rate of the spring. The installed rate with shackles may easily be 50% higher or lower than the original rate. The modified rate with shackles depends upon the position of the shackle, camber of the spring, rate of the spring, load on spring and the length of the shackle. Charts have been calculated experimentally relating the geometric deflection and the spring stiffness for different shackle angles.

Windup of springs – Spring are mainly designed to carry the vehicle load and external vertical forces due to potholes and uneven road but in many applications the springs are also loaded by horizontal forces along the direction of motion or perpendicular to the direction of motion. Any force applied above or below the spring seat would result in a torque which would cause the spring to rotate about the axis perpendicular to the direction of motion and passing through the center of the spring which is shown in figure 2.10.



Figure 2.10 - Windup of symmetric spring. Adapted from [22]

Torque in longitudinal vertical plane is called windup and it produces rotation in the spring shown in the figure 2.10. This torque may be due to braking of the axle or horizontal forces above or below the spring as in Hotchkiss drive suspension. The vertical motion of the spring is restrained by the spring stiffness k(N/mm) and the rotation of the spring is restrained by windup stiffness $\omega(N * mm/rad)$. For a symmetrical spring in which the length of the spring from the clamp towards both the ends is equal the vertical load does not produce rotation and the torque produces no vertical deflection. The windup stiffness can be derived in the manner shown below.

$$P_T = \frac{T}{L} \tag{2.9}$$

$$f = \frac{P_T}{0.5k} = \frac{T}{0.5kL}$$
(2.10)

$$V = TAN V = \frac{F}{0.5L} = \frac{T}{0.25kL^2}$$
(2.11)

WINDUP STIFFNESS
$$\omega = \frac{T}{V} = \frac{kL^2}{4}$$
 (2.12)

The stress due to windup stiffness is expressed by the windup angle V as

$$S_{\omega} = \frac{2Et}{L} * V * SF \tag{2.13}$$

The equation 2.13 can also be expressed by torque T as

$$S_{\omega} = \frac{8Et}{kL^3} * T * SF = \frac{2T}{kL} * \frac{S}{f}$$
 (2.14)

where S is the stress caused by the deflection f, SF is the stiffening factor and V is the windup angle.

The formula 2.14 indicate the importance of length in distribution of stresses due to rotation which is inversely proportional to L and the effect of length on windup stiffness which is inversely proportional to L^2 which can be seen in formula 2.12. Hence large leaf length increases the windup stiffness and decrease the stress in the spring. It is always not possible to make leaf spring semi elliptic (symmetrical) due to non-availability of design space and to obtain desired geometry which leads to unequal spring length on either side or adding one or more leaves to one side. In such unsymmetrical springs, applied torque would lead to vertical displacements or vertical load will lead to rotation of the spring. The figure 2.12 shows the deflection and rotation coupling in an unsymmetrical spring.



Figure 2.11 - Vertical displacement and rotation coupling in unsymmetrical spring. Adapted from [22]

Twist of springs – Other factor to consider while designing is the twist of the spring which may occur due to pothole or/and obstacle under one wheel of an axle. Twisting of leaf spring by α degrees in length l will produce a shear stress of

$$S = \frac{1400t\alpha}{l} MPa (Aprrox.)$$
(2.15)

And torque:

$$T = \frac{420wt^3\alpha}{l} N * mm (Approx.)$$
(2.16)

To keep the length of twist as long as possible the clips used to hold leafs together for alignment should not stop the main leaf from twisting. With the shackles and brackets being flexible the stresses developed due to twisting of the spring would reduce.

3. MANUFACTRING OF LEAF SPRING

An off the shelf leaf spring of Ford F150 was used for making the composite prototype. The spring consisted of 3 leaves but only the 2nd and the 3rd leaf were made using composites and the first leaf was kept the same for hybrid leaf spring. The first leaf or the main leaf consists of circular ends which are used to mount the spring on the chassis and manufacturing the first leaf with integrated fasteners for mounting is beyond the scope of the study. Hence to reduce the complexity of the design the first leaf was kept the same and the other leafs were made of composites.

The method for manufacturing was decided to be autoclave curing of glass fiber prepreg due to high cost input for manufacturing the dies for compression molding or resin transfer molding. Glass fiber being cheap and easily available than carbon fiber was chosen for the choice of the prepreg. The prepreg was bought from rockwest composites with the properties given in table 3.1.

Fiber	64% 300 gsm Fiberglass E-Glass
Resin	36% Newport 301 epoxy resin system
Roll Width	40''
Cure ply thickness	0.011"
Cure temperature	Between 250°F to 300°F

Table 3.1 – Glass Fiber prepreg properties

3.1 Fixture Manufacturing

Fixtures were designed before manufacturing the leaf spring which were common for the static and fatigue test. These fixtures allowed the ends of the leaf spring to displace horizontally with the deflection of the leaf spring hence allowing the change in horizontal length of the spring with its vertical displacement. They also constraint the motion of the spring along the rail direction.

The figure 3.1 shows the final CAD used for manufacturing of the fixtures with all the components together.



Figure 3.1 - Isometric CAD view for designed fixtures

The side plates for the fixture were cut using waterjet from a big steel plate of 0.625 in thickness. Two similar plates were cut and welded together with another rectangular plate in between them for connecting the two side cut plates. The width of the plate was 150 mm and can be chosen different but must be larger than the width of the leaf spring to be tested for space constraints. Shafts are then press-fit in the welded assembly shown in figure 3.3 using a hydraulic press. The diameter of the shafts is decided from the maximum bending moment occurring from the loading and the corresponding stresses on shafts are kept below the yield stress of steel which is 250 MPa.



Figure 3.2 - Cutting of side plate using waterjet process



Figure 3.3 - Isometric view of side trolley of fixture

Wheels of the fixture were then machined on a CNC lathe from cold roll steel giving high dimensional stability. The dimensions of the wheel can be arbitrarily chosen but the center hole dimension of the wheel needs to match the axle of the fixture for press fit. The step in the wheel is created to avoid the derailment of the wheels just like in a train. The axle must be press fit in the fixture but for the wheels the axle can be loose fit with the wheel and a c clip was used to avoid the motion of the wheel along the axis of the shaft. The rails were chosen to be of rectangular cross section with width more than the width of the wheel to be supported.

The fixture once assembled is then sand blasted to give a nice smooth finish for painting. The image of the fixtures assembled with leaf spring supported on them is shown in figure 3.4.



Figure 3.4 - Fixture and leaf spring assembly

3.2 Fixture FEM Simulation and Laser Scanning of leaf spring

A fem simulation was done to find if the metal fixtures would yield with the maximum application of force on the fixtures. Tie contacts were established between any contact surfaces to find the max stresses that would occur with the application of force. The wheel was fixed with all degrees of freedom and the vertical force was applied to the v notch line of the surface. Maximum force anticipated on the whole system was 10000 N and hence the force applied on each fixture was 5000 N which is equal to 2500 N on each notch line. The von-mises stresses from the simulation are shown in figure 3.5.



Figure 3.5 - Stress distribution in the fixture due to maximum loading

The max observed stress was 127 MPa and just below the notch. Since the max stress was below the yield stress of the metal which is around 250 MPa, the fixtures were deemed safe to use.

Before manufacturing the mold from machining for the layup of the leaf spring the geometry of the leaf spring was found using an optical co-ordinate measuring machine as shown in the figure 3.6. The dimensions of the leaf spring were then determined from the obtained surface geometry from laser scanning. Using the dimensions a CAD model was created for machining. Laser scanning was only done for the second leaf due to its curved nature and the dimensions of the third leaf were measured using a calliper and a scale due to its flat shape for making the composite leaf.



Figure 3.6 – Laser scanning the geometry of leaf spring

3.3 Tool machining and part trimming

Renshape 5065 which is a high temperature tooling board was chosen as the tool for the layup instead of aluminum due to its less density as compared to aluminum. Lifting aluminum and placing it in the autoclave would have been very difficult due to its weight. The board came in the size of 24" x 60" x 2" and was cut in steps and glued together using RenLam 4017 / Ren 1510 High-Temperature Laminating System and let cure for a day to ensure perfect bonding between the different layers of the laminate. The tooling board was then machined in a 5 axis CNC to obtain the required mold shape for layup.



Figure 3.7 - Machining of the tooling board



Figure 3.8 - Machined tool for layup

Before the layup of the unidirectional plies the mold was sealed with chemlease sealer due to the porous nature of the mold. Fiberglass plies are cut unidirectional along the fiber direction on the Gerber table with width and thickness more than that of the leaf spring. The extra width can be decided arbitrarily and can be trimmed later the CNC machine by making a trimming tool. However the thickness is not decided arbitrarily and the thickness of the composite leaf should give an equivalent stiffness of the steel leaf. The stiffness of the cantilever beam fixed at one end with the transverse load application at the other end is given by the formula 3.1.

$$\delta = \frac{PL^3}{3EI}, \qquad \qquad K = \frac{P}{\delta} = \frac{3EI}{L^3}$$
(3.1)

Since the length of the composite leaf is equal to that of steel leaf and to have the same stiffness of steel and composite leaf the product of EI should remain constant. The moment of inertia of the beam is given by the formula 3.2.

$$I = \frac{bh^3}{12} \tag{3.2}$$

Where b is the width and h is the thickness of the beam. Since the width is kept constant the quantity Eh^3 should be constant.

So with the decrease in young's modulus as in case of fiberglass, the thickness of the composite leaf should be increased to have the same effective stiffness. The new thickness of the fiberglass beam was calculated using the formula 3.1 and the required number of plies were then cut and

layed up for curing. Due to the porous nature of the tool envelope bagging was done to ensure no leaks exists in the bag. Breather was put all over the tool to avoid the vacuum bag getting a cut from any sharp edges of the tool.

Before the part was put in the autoclave to cure a sample flat part with much smaller dimensions but with the same number of plies and the tool was put in the autoclave with thermocouples and cured. The thermocouples were put on the top ply of the part away from the tool and the temperature of the thermocouple was monitored. For thick laminates, temperature gradient along the thickness direction is high and hence the top ply and the bottom most ply would have different temperatures with top ply being at low temperature from the bottom ply due to the heat flow from the tool to the laminate and hence it is important that the top ply reaches the recommended temperature for curing. From the temperature data obtained from thermocouples the cure cycle is modified to ensure the temperature of the top ply of the laminate follows the recommended cure cycle.

Recommended cure cycle is 50 psi; 3°F/min ramp to 275°F; hold for 60 minutes, cool to <140°F but the cure cycle was modified to ensure top ply follows the recommended cure cycle for the required time.



Figure 3.9 - Trimming of the composite leaf

High pressure causes the resin and fibers to flow outwards leading to uneven thickness of the part and extra width of the part than the width of the prepreg. The extra width had to be trimmed to obtain the required dimensions. A trim tool was made of wood for carrying out the trimming operation and drilling of the holes to clamp all the leaves together was done using a 5 axis CNC machine as shown in figure 3.9. Steps were made at the end of the leaf to duplicate the thickness reduction along the end of the leaf. Thickness along the width of the leaf should be maintained uniform to ensure uniform contact between the third and the second leaf or the top surface would be stressed differently along the width due to non-uniform thickness. Brass shims could be cut into required shape and placed on top while curing to ensure a straight surface or a negative tool can be made which will be in contact with the layup to ensure uniform thickness along the width of the leaf. Double sided tape was used to hold the leaf spring with the wooden tool and small depth of cut was provided to ensure low forces so that the leaf does not separate from the tool.

The thickness calculation of the third leaf utilized the same method used for second leaf except the third leaf had a taper and to account for the effect third leaf was made in a step fashion as shown in figure 3.10. Since the leaf used for multi stage spring the third leaf had a flat surface it was layed up on the aluminum tool for curing in the autoclave. The third leaf was then trimmed in the CNC to the required width. The final assembly of the composite hybrid leaf spring is shown in the figure 3.10.



Figure 3.10 - Assembled hybrid leaf spring

3.4 Problems while manufacturing leaf spring

The leaves were aligned with the hole and clamped together with the help of a bolt with a required bolt torque. With the application of torque more than 100 lb.ft cracking of the third leaf was observed as shown in the figures 3.11 and 3.12.



Figure 3.11 - Cracking of composite 3rd leaf



Figure 3.12 - Observed damage due to curved surface and high bolt torque

The cracks had propagated throughout the thickness of the third leaf rendering the spring incapable of carrying load. The cracks were observed due to the low compressive strength of the composite

and had propagated through the thickness of the leaf with the tightening of the bolt. Several other factors contributed to the propagation of the cracks which included not using washers and no transverse ply to avoid the propagation of the cracks through thickness. The leaf surface was curved at the top leading to non-uniform contact of the bolt with the leaf which led to non-equal distribution of load across the surface which then led to stress concentrations. Also the leaf was not reinforced with cross plies and hence if any crack originates it could easily propagate in the thickness direction through matrix. Cross fibers would have avoided the propagation of crack through the thickness of the leaf. The microscopy image of the crack along the surface is shown in figure 3.13.



Figure 3.13 - Microscopy of cracked surface

To ensure that the problem does not occur again the plies for the third leaf were layed up again but with silicon dams around the layup. The silicone dams made sure the resin spill from pressure is limited to the dams surrounding them and high curvatures on the top part are avoided. The layup was also reinforced with cross plies to ensure crack does not propagate through the thickness of the layup. A cross ply was used every 10 plies of unidirectional 0° plies. Figure 3.14 shows the use of silicon dams around the layup.



Figure 3.14 - Use of silicone dams to avoid resin spill

The part was then cured and then the top surface of the laminate was face milled in the CNC to ensure flat portion of the leaf surface for equal distribution of forces. Washers were used in the final assembly and a lock nut was used instead of the regular nut to ensure the assembly does not come apart with vibrations. Bolt torque applied was 70 lb.ft which was less than the original applied torque. The figure 3.15 shows the leaf spring after assembly. The weight of the assembly was reduced from 55 lb. to 36 lb. leading to 35% weight reduction using composite leaves.



Figure 3.15 - Leaf spring assembly after replacing cracked third leaf

4. **RESULTS**

4.1 Results for mechanical properties of glass fiber laminates

The mechanical properties of glass fiber reinforced laminate with Newport 301 resin system have been found to characterize the laminate. Tensile tests were done to find E_1 , E_2 , v_{12} and G_{12} and the corresponding strength using the prescribed ASTM standard. The tabulated properties are given in table 4.1.

Parameter	Average	Standard deviation	ASTM Standard
E_1 (GPa)	34.84	0.81	
$E_2(\text{GPa})$	10.13	0.49	
ν ₁₂	0.33	0.02	D3039
X_{1T} (MPa)	889	29	
X_{2T} (MPa)	67	2	
G ₁₂ (GPa)	3.15	0.03	D2519
X_{12} (MPa)	55	0.5	D3318

Table 4.1 - Characterized mechanical properties of glass fiber laminates

Six samples for each property were tested and the average property was calculated. The thickness of each ply was measured to be approximately 0.28 mm. The layup done for measuring the young's modulus in fiber direction, transverse to fibers and for the shear modulus was [0]₄, [90]₈ and [45/-45]_{4s} respectively. The strains were measured using DIC for calculating the young's modulus and poisons ratio.

The figures 4.1-3 show the stress vs strain graphs for different loading and figures 4.4-6 show the failure locations of specimens for the specified loading.



Figure 4.1 - Stress vs Strain for loading in 1 direction



Figure 4.2 - Stress vs Strain for loading in 2 direction



Figure 4.3 - Stress vs Strain for shear loading



Figure 4.4 - Failure of specimens from loading in 1 direction



Figure 4.5 - Failure of specimens from loading in 2 direction



Figure 4.6 - Failure of specimens from shear loading

4.2 Experimental setup

The test setup consisted of a hydraulic actuator for carrying out static and fatigue tests. The hydraulic actuator was hinged at the top point of the I beam and to stabilize the actuator in cyclic motions strands of steel wire were attached between the load frame and the actuator. The figure 4.7 shows the actuator with the leaf spring and the fixture assembly.



Figure 4.7 - Experimental test setup

The four steel wires are attached using turnbuckle with the actuator and are kept in tension to ensure fix position of the loading setup for the vertical motion of the actuator. An actuator with the capacity of 10 Kip was used and concrete blocks were placed on the floor to ensure the correct vertical position of the spring for deflection. The rails were stuck to the concrete with gypsum and the leaf spring was supported on the moving cart fixtures positioned on the rails.

Static and fatigue test both were carried out using the setup. For the static tests the center portion of the leaf spring was not clamped to find the true stiffness of the spring. While fatigue tests were carried out using the actuator the center portion of the leaf spring was clamped to mimic the condition of the leaf spring in the automobile. The max stroke of the actuator was limited to 6 inches and the max frequency attainable changed with the stroke required. To increase the stroke of the actuator when required in testing spacer block was placed at the top of the spring thus increasing the effective displacement of the spring by the thickness of the spacer block.

4.3 Static and fatigue testing of metal and hybrid leaf spring

Ford F-150 leaf spring was bought from the dealership and tested in static and fatigue conditions and the results were compared with those of hybrid spring. The spring was a two-stage spring meaning the third leaf came in contact completely after applying a certain amount of load. The stiffness of the spring increases continuously till the third leaf contacts the second leaf completely and then remains constant. The stiffness of the spring in the unclamped and clamped condition was tested by mounting on the test fixtures developed for the loading. The true stiffness of the spring is found from the unclamped condition since the spring is free to deflect without any constraints. When the spring is mounted on the vehicle it is clamped with the axle of the vehicle using a U bolt which avoids the relative motion between the spring and the axle. This clamping however influences the stiffness of the spring since the center region of the spring is clamped hence rigid and since the stiffness of the spring is inversely proportional to the length cube the stiffness of the spring increase with the clamping of the spring.



Figure 4.8 - Deflection of spring in unclamped condition

The hydraulic actuator in figure 4.8 can be seen pushing the steel spring with a plate to ensure the equal distribution of forces on the loading area. The hybrid spring was made by replacing the second and the third metal leaf with corresponding composite leaves with thicker leaves to ensure same stiffness as metal leaves. The first leaf was kept the same since end mountings were complex

to manufacture and had to be bolted with the composite leaf which would introduce another failure location.



Figure 4.9 - Loading of composite spring in unclamped and clamped condition

The composite spring shown in the figure 4.9 is also tested for stiffness in the unclamped and clamped condition. The clamp shown in the figure 4.9 was kept loose for unclamped condition testing and tightened for clamped condition testing. The stiffness graphs for both the conditions are shown in figure 4.10.

The slope of the load displacement curve gives the stiffness of the spring. The initial slope of the hybrid leaf spring is less than that of metal spring which can be seen from the decrease in load carrying capacity of composite spring with displacement. The table 4.2 helps understand the difference in stiffness of the metal and hybrid leaf spring in different stages of action.



Figure 4.10 - Load vs Displacement of metal and composite leaf spring in unclamped condition

	Stage 1 stiffness (N/in)	Stage 2 stiffness (N/in)
Metal	953	1093
Hybrid	816	1013

Table 4.2 - Unclamped stiffness of metal and hybrid leaf spring

The difference in the stiffness in 1st and 2nd stage is due to third leaf coming in complete contact of the second leaf. The thickness of the composite leaves was higher to ensure the same stiffness of the metal leaves but due and fiber flow during the curing of the leaves, thickness was distributed unequally at the top surface along the width which led to the decrease in the stiffness in the first stage of the spring where only 1st and the 2nd leaves are active. The third leaf was made in a step fashion to replicate the gradual decrease of thickness along the length of the leaf. The deviation from uniform decreasing thickness is the reason for decreased stiffness in the 2nd stage of the spring. The stiffness of the spring was also calculated in the clamped conditions for both the metal and hybrid spring and figure 4.11 shows the behavior of springs in the clamped condition.



Figure 4.11 - Load vs Displacement of metal and composite leaf spring in clamped condition

	Stage 1 stiffness (N/in)	Stage 2 stiffness (N/in)
Metal	1048	1210
Hybrid	930	1128

Table 4.3 - Clamped stiffness of metal and hybrid leaf spring

The clamped stiffness is found to be higher than the unclamped stiffness due to the reduced active length of the spring from clamps. The steel spring was then tested in cyclic loading with cyclic displacement ranging from 3 to 5.5 inches (2.5 in stroke) in a displacement control mode with a frequency of 0.75 Hz. The maximum stroke of the actuator was 6 inches and being first test with unknown behavior of spring it was not loaded to 6 inches but 5.5 inches. The test was then run for 1 million cycles which took almost 3 weeks to complete. The figure 4.12 show the change of stiffness with fatigue cycles.



Figure 4.12 - Stiffness vs cycles for metal spring, 5.5 in max displacement

The stiffness of the spring is almost constant throughout the test with minor fluctuations but not significant. The spring withstood 1 million cycles of cyclic loading without any observable damage and successfully deflected back to the original position after the end of the test indicating no plastic deformation in the spring. An initial spike is observed in the stiffness of the spring which is due to the spring position adjustment to the cyclic loading. The spring is said to have passed the test at the given loading as no damage was observed and the stiffness of the spring is almost constant during the test.

The hybrid spring was tested next and to maximize the failure possibility of the spring it was loaded with an actuator cyclic displacement range of 3.5 to 6.5 inches. The frequency of cyclic loading was kept the same as 0.75 Hz. The figure 4.13 show the stiffness variation with the test cycles.



Figure 4.13 - Stiffness vs cycles for hybrid spring, 6.5 in max displacement

The test is also run for 1 million cycles which took almost 3 weeks and the stiffness of the hybrid spring also remains same over the course of the test. The spring deflected back to original position indicating no plastic deformation in the spring.

The stroke of the actuator was limited to 6 inches and to load the spring further than 6 inches a spacer block of thickness 2 inches was placed between the spacer plates of the spring. The spring is at zero deflection with one spacer plate and with the addition of spacer plates of thickness 0.5 inch and spacer block of thickness 2 inch the spring could be loaded to a max displacement of 8.5 inches which induces negative curvature in the spring. This is the extreme case of loading in the spring since negative curvature of the spring are generally not encountered in practical conditions. They are only encountered when the truck is loaded more than the capacity it is designed for. The metal spring was loaded quasi-statically in hope it would break and the data from the experiment would be used to calculate the loading displacement for the hybrid spring. Surprisingly the spring did not break in quasi-static loading and the spring was then loaded for cyclic displacements of 3 to 6 inches of the actuator. It should be noted that the spring is deflected by 2.5 inches at zero stroke of the actuator due to the thickness of spacer block and plates and the actual cyclic



Figure 4.14 - Metal spring being loaded using spacer block and plate to enhance displacements



Figure 4.15 - Stiffness vs cycles for metal spring, extreme loading

displacements of the spring account from 5.5 to 8.5 inches. The figure 4.14 shows the extreme displacement applied to spring with the spacer block and plates.



Figure 4.16 - Load vs cycles for metal spring, extreme loading

At such extreme loading also the spring stiffness was found to be constant with the number of cycles of test. The test was stopped at 650k cycles after no significant damage was observed to spring. The max and the min load also remain almost constant during the test indicating the spring can still withstand the designed load at such extreme loading. The composite spring was subjected to same displacement loading and stiffness, max and min loads are shown in figures 4.17 and 4.18.


Figure 4.17 - Stiffness vs cycles for hybrid spring, extreme loading



Figure 4.18 - Load vs cycles for hybrid spring, extreme loading

The stiffness and the load graphs follow the similar results of the steel spring and no decrease is observed either in stiffness or load capacity of the spring. The spring deflected back to the original shape after withdrawal of load indicating no plastic deformation in the spring. The test was stopped around 800k cycles as no damage observed over the course of the test. Since the test is displacement control and stiffness of the steel spring is more than the composite leaf spring the load carried by the steel spring is more than what carried by the composite spring.

Strain gauges were also placed on the steel and the hybrid spring to find out the strain just outside the clamping region which would be highest along the length of the spring due to similar action like a cantilever beam. The motive behind placing the strain gauges was to find the max strain and hence stress in the main leaf of the spring and compare it with the yield and the ultimate tensile stress of the metal. The strains linearly increase with the deflection of the spring and obtains the maximum value with the max deflection of the spring. The average strains from both the strain gauges for both the metal and the hybrid spring are shown in table 4.4.

Table 4.4 - Stress and strains adjacent to clamping region

	Metal	Hybrid
Strain (με)	3999	4180
Stress (MPa)	800	836



Figure 4.19 - Location of strain gauges on the main leaf

The location of strain gauges can be seen in the figure 4.19 which is just outside the clamping plate on both the sides. The stresses in steel spring were found to be more than the hybrid spring since the main leaf of the hybrid spring is deflected more than that of steel due to higher thickness of the 2^{nd} and 3^{rd} leaf of the hybrid leaf spring than that of the metal spring. The composite leafs of spring were made thicker to obtain the same stiffness of the steel spring. This increased thickness is accounted for higher displacement of the main leaf of the hybrid spring for the same initial position and displacement of the actuator.

The yield strength of steel springs (SUP 11A) is generally between 1100-1200 MPa and the tensile strength of the spring steel is very close to the yield strength. From the data obtained by the strain gauges, the spring was loaded to nearly 73% of the yield strength. It was thought that the stresses are below the endurance limit which is 50% of the tensile strength [23] as the spring did not fail for a total of 1.5 million cycles but the observed stress of 800 MPa is more than the 600 MPa (50% of 1200 MPa). The possible reason for the effect is the introduction of compressive residual stresses induced from shot peening at the time of manufacturing the metal leaf spring in industry which lower the max stress in the leaf. The spring was not loaded further as it had been tested for negative curvatures which is extreme form of loading for leaf springs. Loading it even further and failing it would not reflect the actual design loads and conditions. To study if the fatigue life of the leaf spring is just due to steel leaf and if making a composite main leaf would affect the fatigue performance it was decided to perform fatigue tests on lab small scale fatigue samples as a function of aspect ratio in a displacement-controlled mode. They were loaded to almost 85% of the failure strength to observe the failure of specimens as a function of test cycles and properties such as stiffness, max and min load were monitored for the test. The test was done for aspect ratio of 10 and 30 to observe if aspect ratio influences the failure cycles and mechanism. The aspect ratio of 10 and 30 were chosen as the aspect ratio of 20 is the cutoff for Euler Bernoulli beam theory after which the shear forces can be neglected for failure. The main aim of the lab scale experiments was to conclude that if the composite beams withstood the required number of fatigue cycles at a given load then the actual scale all composite leaf spring would not fail in fatigue under the same stress range keeping the same aspect ratio of the samples.

4.4 Fatigue testing of composite beams with Aspect Ratio 10

Specimens with a span length of 3 in and thickness of 0.3 in with a width of 0.5 in were made to obtain an aspect ratio of 10. The samples were first tested quasi-statically and then in fatigue to observe the effect of fatigue cycles on the stiffness of the specimens. Since the aspect ratio for the samples is lower than considerations for Euler Bernoulli beam theory it is expected that shear would play a dominant role in failure of specimens quasi-statically as well in fatigue. The samples were tested using 3-point bending fixtures in a 5 Kip hydraulic machine.



Figure 4.20 - 3-point flexure fixture for composite specimens

The results for the quasi-static flexure failure for the samples with aspect ratio of 10 are shown in the figure 4.21.



Figure 4.21 - Failure of samples quasi-statically, Aspect Ratio 10

The max loads and the corresponding displacements for failure are shown in the table 4.5 and failure location of specimens are shown in figure 4.22 and 4.23.

Sample	Failure Load	Failure Strength (MPa)	Disp. at Failure	Flexure stiffness
No.	(N)		load (mm)	(N/mm)
1	4720	741	3.95	1436
2	4562	716	4.09	1344
3	4820	757	4.45	1355
4	4760	747	4.23	1351
Avg.	4714.5	740	4.18	1371.5

Table 4.5 - Max load, corresponding disp. and stiffness for flexure samples, Aspect Ratio 10



Figure 4.22 - Side view of samples failed quasi-statically, Aspect Ratio 10



Figure 4.23 - Bottom view of samples failed quasi-statically, Aspect Ratio 10

The figures 4.22 and 4.23 show the failure modes to be combination of shear failure and fiber breakage due to tensile stress. For sample 1 tested statically the failure was predominantly shear which can be observed from the sample breaking into two pieces. The crack initiates at the outer end of the sample and then propagates towards the middle of the specimen due to the presence of shear forces in the specimen. The other 3 samples failed due to combination of shear and fiber breakage which is evident form the bottom tensile surface of the specimen. Stress concentrations were observed at the loading tip and the material deformed due to stress concentrations which can be seen from the figure 4.22. Distribution of forces along a surface would also cause stress concentrations at the ends of surface and hence stress concentrations would always exist.

The samples are cyclically loaded between 25% and 84% of the max average displacement found from the static test on a displacement control hydraulic machine and the dynamic cyclic stiffness, max and min loads are monitored to understand the failure mechanism. The figures 4.24-27 help understand the variation of stiffness for different samples as a function of test cycles.



Figure 4.24 - Stiffness vs cycles for specimen 1, Aspect Ratio 10



Figure 4.25 - Stiffness vs cycles for specimen 2, Aspect Ratio 10



Figure 4.26 - Stiffness vs cycles for specimen 3, Aspect Ratio 10



Figure 4.27 - Stiffness vs cycles for specimen 4, Aspect Ratio 10

The stiffness vs fatigue cycles graphs for all the four samples show degrade in stiffness with the increase in cycles. There can be seen an abrupt drop in stiffness for all the samples which signify propagation of crack due to shear forces. For sample 1 and 2 the propagation of crack and decrease

in stiffness occurs at the later stage of the test after 5k cycles with first gradual decrease in stiffness of the specimen due to material deformation from the stress concentration at the loading tip. The decrease in stiffness also signify the decrease in the load carrying capacity of the beam for the same displacement. For sample 3 and 4 the decrease in stiffness was more sudden within first few thousand cycles and then the decrease was more gradual again due to material deformations from the stress concentration at the loading tip. The figures 4.28 and 4.29 show the specimens after the cyclic loading and the failure locations.



Figure 4.28 - Side view for failure of specimens in cyclic loading, Aspect Ratio 10



Figure 4.29 - Top view for failure of specimens in cyclic loading, Aspect Ratio 10

For all the four samples shown in the figure 4.28 and 4.29 which failed in fatigue, the delaminations are clearly visible and no sign of fiber breakage is observed at the tensile surface of the specimens. The stress concentrations introduced at the loading tip play a significant role in failure of the

specimens. The gradual decrease in stiffness of the samples is observed due to the material deformation at the loading tip. The deformation also provides a starting point for the crack to propagate in shear which can be clearly seen as in the case of sample 2, 3 and 4 where the crack initiates at the center of the specimen and then propagates outwards towards the end of the specimen. In case of sample 1 complete shear failure is observed and the crack originates from the end and then propagates towards the center of the specimens.

4.5 Fatigue testing of composite beams with Aspect Ratio 30

Specimens with same span length but reduced thickness were made to have an aspect ratio of 30. 5 specimens were tested in a quasi-static manner to establish flexure stiffness and strength. Other specimens were then tested for cyclic loading with displacement control to observe the effect of stiffness as a function of fatigue cycles and residual strength were measured to compare the stiffness of the samples before and after the cyclic loading. The figure 4.30 shows the results for the quasi-static testing of the samples.



Figure 4.30 - Load vs Displacement for quasi-static testing, Aspect Ratio 30

Sample No	Fracture Load (N)	Fracture Strength (MPa)	Disp. At fracture load (mm)	Bending Stiffness (N/mm)
1	1041	1112	11.41	108
2	1116	1198	11.77	115
3	1049	1126	12.14	108
4	1058	1136	12.82	104
5	1008	1082	12.82	101
Avg.	1054.4	1131	12.19	107.2

Table 4.6 - Results for failure load, displacement and sample stiffness, Aspect Ratio 30

The table 4.6 shows the strength and the flexure stiffness for the samples tested. The samples were tested in cyclic loading with displacements ranging from 6 mm to 10 mm with a cyclic frequency of 5 Hz. Since the displacements are linearly related with the load applied, the samples were tested in the load ranging from 50% to 82% of the failure load. Several issues were observed with cyclic testing of the specimens. Firstly, the free rotational motion of the lower machine jaw from the vibrations due to high cyclic frequency led to rotation of the lower machine jaw which led to the fall of samples from the fixtures since they were simply supported. To overcome the problem a vertical prismatic joint was made and connected to the lower jaw to avoid rotation and allow only translation of jaw in vertical direction. The figure 4.31 shows the attachment done with the lower jaw for constraining the rotational motion.



Figure 4.31 - Prismatic connection to ensure vertical motion of the jaw

This alone did not solve the problem of the samples falling out of the fixture and even slight rotational motion would create the specimen to distort and then finally fall out. This required continuous monitoring of the samples and adjusting the position when required which would lead to interfered load data and hence incorrect stiffness. To solve the issue supporting pins were made with slots in between to hold the sample which would avoid any motion of the samples. Also, double sided tape for pins and holding springs at pin ends of high stiffness were used to avoid any motion of the sample in cyclic loading.



Figure 4.32 - Slotted pin used for holding samples

Four samples were tested in cyclic loading for 150,000 cycles and the change in stiffness, max load and min load was monitored as a function of fatigue cycles. The figures 4.33-36 shows the change in stiffness for the four samples tested as a function of fatigue cycles.



Figure 4.33 - Stiffness vs cycles for sample 1, Aspect Ratio 30



Figure 4.34 - Stiffness vs cycles for sample 2, Aspect Ratio 30



Figure 4.35 - Stiffness vs cycles for sample 3, Aspect Ratio 30



Figure 4.36 - Stiffness vs cycles for sample 4, Aspect Ratio 30

From the images for stiffness vs fatigue cycles for the four samples it is observed that the stiffness of the samples does not change much over the course of the test. Initially the stiffness is low and then abruptly rises since the samples get adjusted in the loading fixture. The variation in stiffness with progression of the test is attributed to the dynamic loading of the sample but more importantly

no sudden decrease in stiffness is observed which would mean the cracks in the sample and the progression of the crack. The image of the sample after the fatigue cycles is shown in figure 4.37.



Figure 4.37 - Bottom view of specimens after cyclic loading, Aspect Ratio 30

From the images shown in figure 4.37 for samples 1, 2, 3 and 4 respectively it can be seen that for the samples 1,2 and 3 there is very minor fiber breakage on the tension side of the flexure sample where as for the 4th sample the fiber breakage for the bottom ply can be seen significant. The fiber breakage was only seen for the bottom ply and no breakage or cracks were observed along the thickness of the specimen. Other significant thing to notice was the ridges created on the samples where the samples were on the fixture. Constant length changes due to bending led to relative motion between the fixture and the specimens led to wear and tear of specimen at the location where it was supported on the fixture.

The max and min load as a function of cycles is also shown in the figures 4.38-41 for the four different samples.



Figure 4.38 - Load vs cycles for sample 1, Aspect Ratio 30



Figure 4.39 - Load vs cycles for sample 2, Aspect Ratio 30



Figure 4.40 - Load vs cycles for sample 3, Aspect Ratio 30



Figure 4.41 - Load vs cycles for sample 4, Aspect Ratio 30

The test was run on displacement control and the resulting load was measured using the load cell on the machine. The initial increase and decrease in max and min load respectively can be attributed to sample adjustment in the fixture. Also for the first few thousand cycles the displacement control is not achieved precisely to the set values and once it reaches the set values after few thousand cycles it becomes stable and the min and max displacements for the cycle remain constant. The max load and min load are observed to be almost same for the start and end of the test which indicated the specimen is still structurally strong to withstand extreme loading.

To validate the structural strength and stiffness of the specimen after cyclic loading the specimens were then subjected to quasi-static loading until failure. The table 4.7 shows the stiffness before and after the cyclic loading and strength of the samples tested quasi-statically after the cyclic loading.

Sample No.	Initial Stiffness (N/mm)	Final Stiffness (N/mm)	Residual strength (MPa)	Average Strength (MPa), no cyclic loading
2	102.5	104.6	1167	1131 (st. dev. 35)
3	100.8	103.3	1215	
4	99.0	99.6	1117	
Avg.			1166 (st. dev. 40)	

Table 4.7 - Initial and final stiffness after cyclic loading comparison for different specimens

All the samples which were tested in cyclic loading were first loaded quasi-statically to find the initial stiffness of the samples to compare with the stiffness after the cyclic loading. From table 4.7 the initial and final stiffness of the samples after cyclic loading does not change and the residual strength is within the standard deviation of initial tested samples even after cyclically loading the sample for 150k cycles. There was minimal fiber breakage observed which seems to not influence the stiffness of the part after the cyclic loading where as in case of aspect ratio 10 the samples failed early with the propagation of crack from the stress concentrations at the loading tip at cycles as low as 30k. The data suggests that with the increase in aspect ratio of unidirectional composite specimens the possibility of fatigue failure is low for simplified shapes and geometries which do not have any stress concentrations.

5. SUMMARY AND CONCLUSION

5.1 Summary

With the advancement of technology and government policies to curb emissions and improve efficiency, the growth in the manufacturing and use of composites has been remarkable leading to reduction in production cost and thus enabling the automotive sector to experiment making different parts using composites. Leaf spring is one of the parts which could lead to huge savings in weight and is being studied from the 1980s. The advancement in the previous decades has been limited to mono leaf spring made using composites and the current study attempts to design and test a composite hybrid leaf spring.

An off the shelf leaf spring for Ford F-150 was chosen for the composite hybrid spring prototype. The composite hybrid prototype was made using replacing all leaves except the first leaf with composite as manufacturing the first leaf with integrated fasteners for mounting is beyond the scope of the study. Static tests were done to compare the stiffness of steel and the composite spring and it was found that stiffness of steel was higher than that of composite due to uneven thickness of composite spring along the width of the leaf and the stepping of the third leaf. Fatigue tests are then carried out on steel and composite leaf spring with extreme deflections which induce negative curvature in the spring. These negative curvatures are not designed for normal loading of the vehicle and cyclic tests were stopped after half million cycles since no damage was observed and the stiffness, maximum and minimum loads carried by the spring were almost constant for both metal and composite hybrid leaf spring. A single fatigue test took nearly 3 weeks to complete. Strain gauges were installed on the steel and composite hybrid spring adjacent to the clamping plates to find the maximum strain during the loading of the spring. The max stress was calculated to be around 800 MPa which was nearly 73% of the yield stress of spring steel. High frequency fatigue testing was conducted on small composite beam specimens to ensure that the long fatigue life of the assembly is not solely due to steel material and if main leaf is replaced by glass fiber composite laminate it would still not fail in fatigue. The aim of the test was to subject the specimen with min 50% and max 85% of failure load cyclically and observe the failure locations and mechanism as a function of aspect ratio for composite beams.

Aspect ratio of 10 and 30 were chosen for the fatigue test of composite beams. The samples were first subjected to quasi-static test to find failure stress and then tested in cyclic conditions. For the samples with aspect ratio 10 it was found that the samples failed in combination of shear and bending stress in cyclic loading. Stress concentrations at the loading tip led to material deformation which then lead to initiation site for crack propagation due to shear. The samples failed at an early stage of cyclic loading at around 5k cycles. Abrupt drop in stiffness was observed which was from crack propagation due to shear forces. Samples with aspect ratio of 30 were subjected to same tests but the number of test cycles were limited to 150k to shorten the duration of the test as the samples did not fail under the same displacement conditions. Flexure stiffness of the composite beams was measured before and after the test and no drop was observed in bending stiffness of the samples after cyclic loading of 150k cycles. Residual strength of the beams was also measured after cyclic loading. The residual strength was found to be within the standard deviation of the strengths of the initially tested specimens without cyclic loading indicating no drop in the strength after cyclic loading of specimens.

5.2 Conclusion

The fatigue testing of samples with aspect ratio 10 and 30 give an insight into failure locations and mechanism. The results for cyclic loading of samples with aspect ratio 30 indicate that with high enough aspect ratio to neglect shear forces and without the presence of stress concentrations the probability of failure of composite structures in fatigue is low in flexure. Extending the same analogy to leaf springs made using composites it can be concluded that keeping a large enough aspect ratio to neglect shear forces with no stress concentrations chances of failure due to fatigue loading are low and leaf springs can be successfully used for automotive applications.

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